

Bandwidth Criteria for Category I and II PIOs

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Background

- Phase II SBIR from Air Force Research Labs
 - Development of Methods & Devices to Predict & Prevent PIO
 - Contract monitor is Tom Cord
 - In process of writing final report
- Goals:
 - Gather data (Lockheed Martin, Northrop Grumman, McDonnell Douglas subcontractors)
 - Analyze all available PIO data
 - Develop criteria for prevention by design
 - Develop test methods for detection in flight test
 - Develop devices for real-time monitoring and detection

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Outline

- Pitch criteria based on airplane Bandwidth for
 - Handling qualities
 - PIO
- Apply research, experimental, operational data
- Compare Smith-Geddes, Gibson, Neal-Smith criteria
- Bandwidth criteria for Category II PIO
- Control/response sensitivity and PIO
- Extension to roll axis
- Recommendations

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Analytical Criteria

- Category I PIOs (linear):
 - Many criteria exist
 - Bandwidth-based criteria show most promise
 - AIAA-98-4335 show them to be effective
 - Amenable to initial design through flight test
- Category II PIOs (rate limiting):
 - Only a handful of criteria
 - Most are complex to apply
 - Require closed-loop analysis
 - Applicable to analytical models only, not in flight
 - Must make assumptions about pilot, frequency, or amplitude
 - Recent work on Bandwidth criteria shows promise

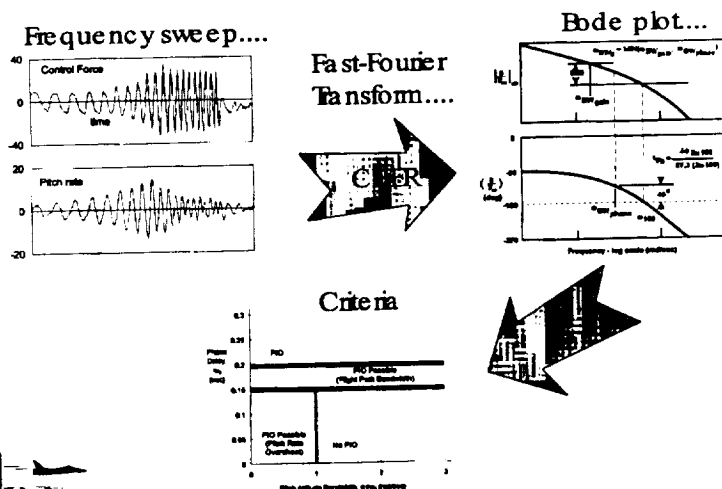
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Handling Qualities Criteria

- Criteria developed for draft MIL standard (AFWAL-TR-82-3081, 1982)
 - Requirements more stringent than "classical" (CAP) criteria
 - Almost didn't make it into MIL-STD-1797 (1987)
- Primary short-term response criteria in rotorcraft handling-qualities standard ADS-33D-PRF
- For airplanes, adopted revised version of Gibson's requirements on dropback/overshoot
 - Relaxed Bandwidth limits (WL-TR-94-3162)
 - USAF TPS project found dropback untestable in flight (AFFTC-TR-95-78)
 - Dropback secondary in importance to pitch rate overshoot
 - Current criteria use frequency-domain measure of overshoot

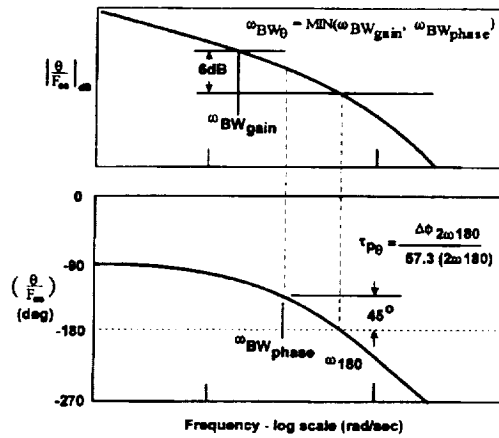
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Process for Obtaining Bandwidth Information from Flight



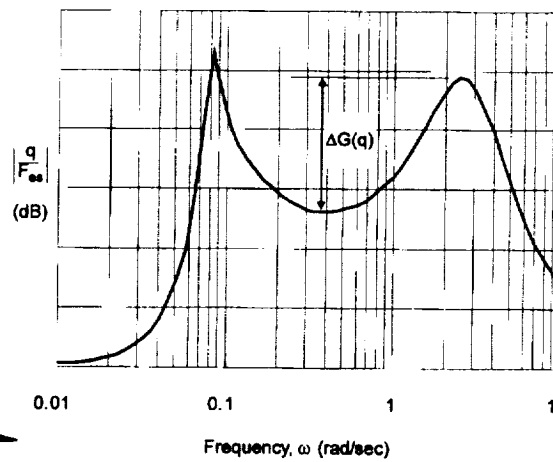
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Attitude Bandwidth Parameters



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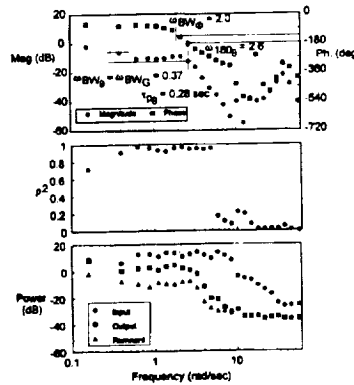
Pitch Rate Overshoot



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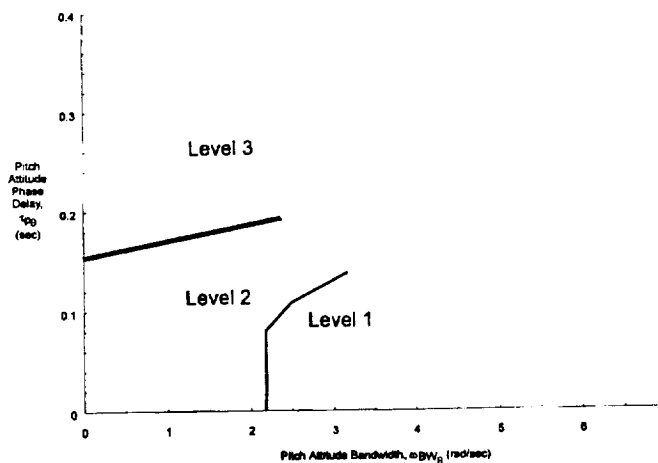
Nonlinearities Can Cause Data Quality to Degrade

- Example data from in-flight frequency sweep
- Coherence drops as a result of rate limiting
 - ρ^2 is a measure of *linear* correlation between input and output
- Input power high
- Frequency response looks reasonable
- Examined in AIAA-99-0639 (Reno)



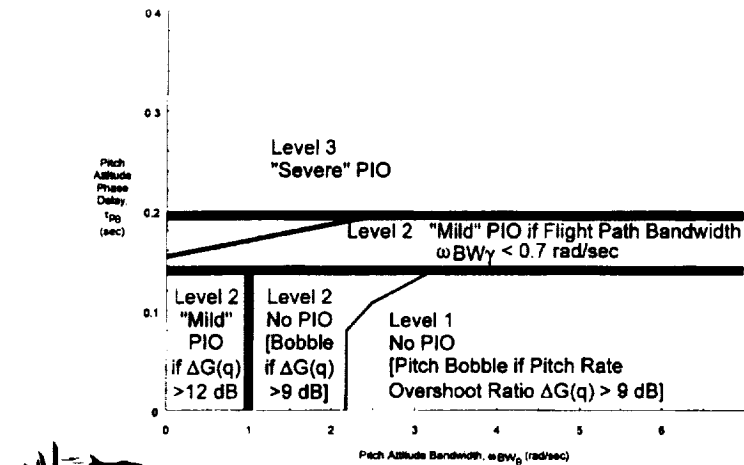
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Bandwidth Criteria for Handling Qualities (Fighters -- Landing)



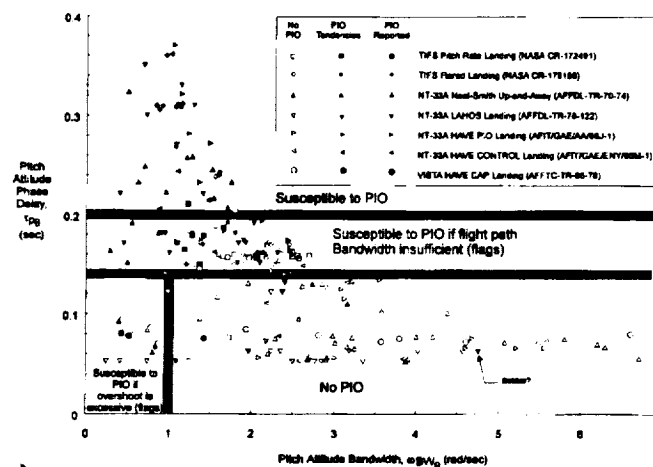
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Bandwidth Criteria for PIO (Fighters -- Landing)



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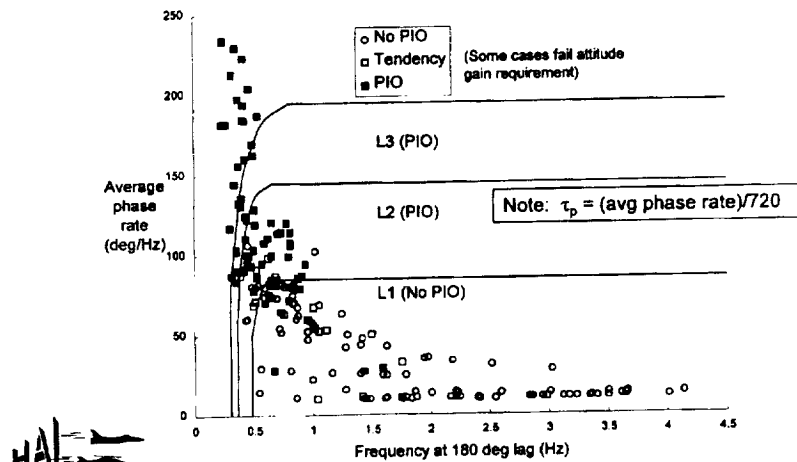
Criteria Applied to Research Data Successful on 188 of 207 (91%) [78 of 91 PIOs (86%)]



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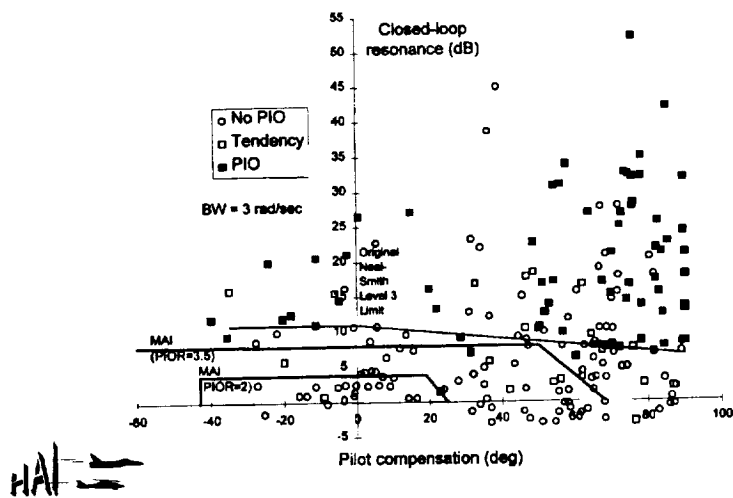
Gibson Criteria (Research Data)

166 of 207 cases (80%) [66 of 91 PIOs (73%)]



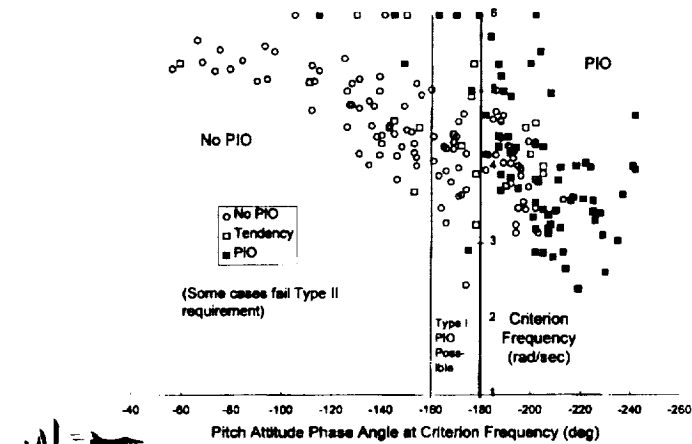
Neal-Smith Criteria (Research Data)

158 of 207 cases (76%) [75 of 91 PIOs (82%)]



133 of 207 cases (64%) [82 of 91 PIOs (90%)]

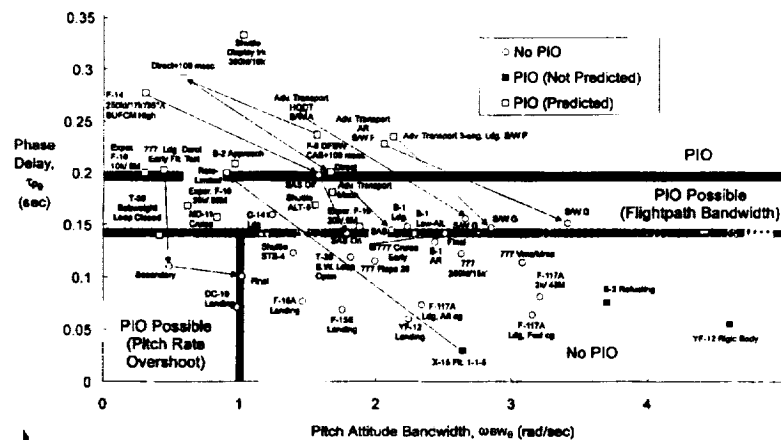
133 of 207 cases (64%) [82 of 91 PIOs (90%)]



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Bandwidth Criteria Applied to Real Airplanes

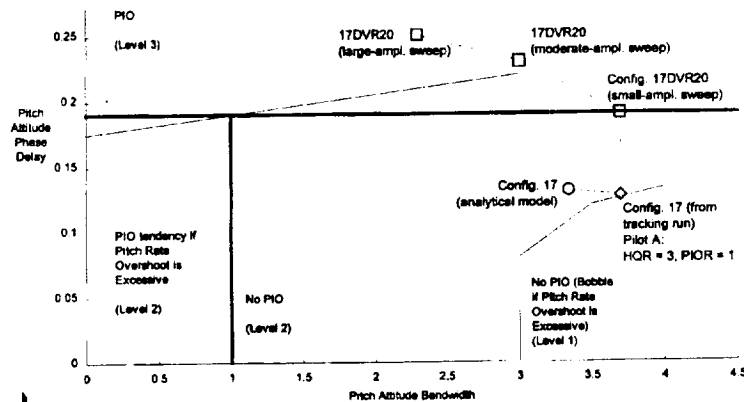
45 of 49 cases (92%) [20 of 24 P|Os (83%)]



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Application to Rate-Limited Configurations

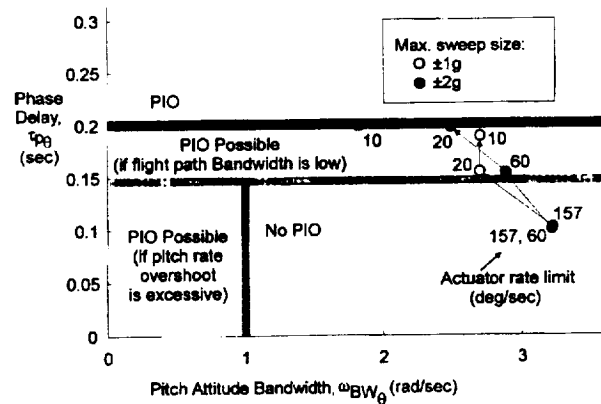
Example: Frequency sweeps from LAMARS simulation
(20-deg/sec RL, unstable open-loop; 1 of 5 pilots encountered divergent PIOs)



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Application to Rate-Limited Configurations

Example: Config. 2D from HAVE LIMITS TPS Project
(RL on stable bare airplane; no PIOs reported for discrete tracking task)

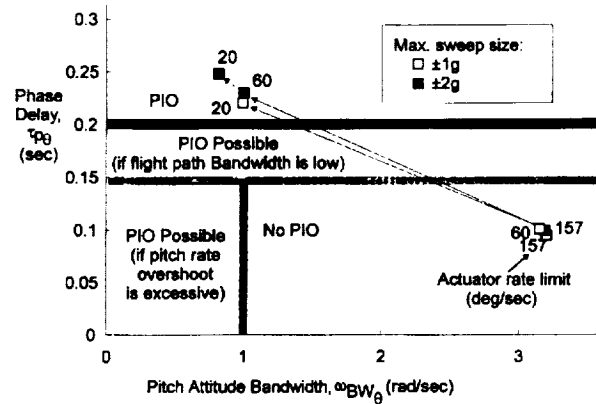


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Application to Rate-Limited Configurations

Example: Config. 2DU from HAVE LIMITS TPS Project

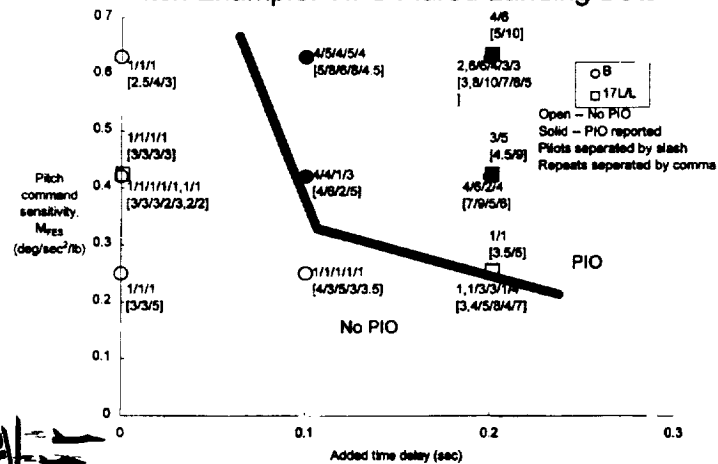
(Unstable open-loop; divergent PIOs for RL of 60 deg/sec and below)



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Inappropriate Control/Response Sensitivity Contributes to PIO

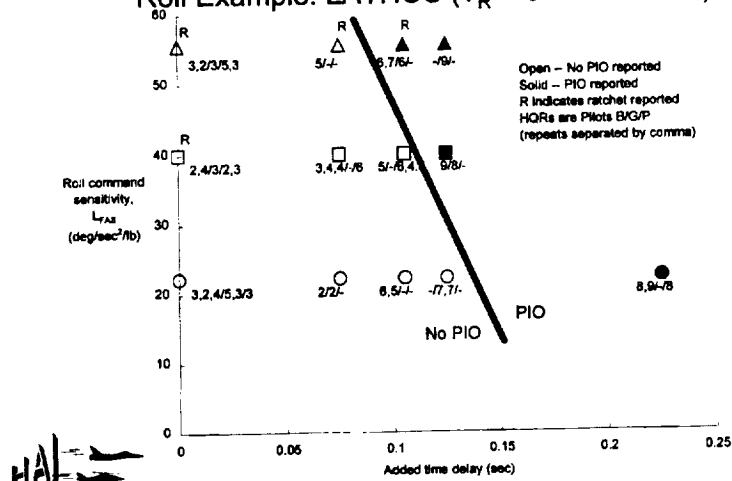
Pitch Example: TIFS Flared Landing Data



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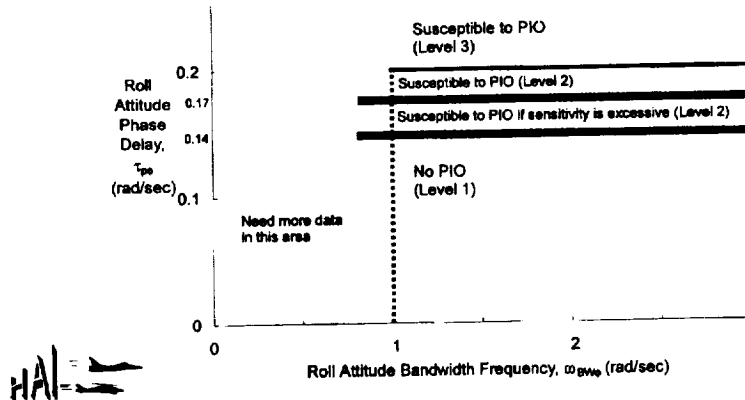
Inappropriate Control/Response Sensitivity Contributes to PIO

Roll Example: LATHOS ($T_R = 0.45$ sec data)



Airplane Bandwidth Criteria for Roll

- Much smaller data base
 - Not as many real experiences
 - Most research experiments did not record PIO ratings
- Limits proposed in WL-TR-94-3162:



Recommendations

- Apply criteria as early in development as possible
- Focus especially on Phase Delay limits
 - No greater than 0.14 sec in pitch or roll
- If feel system dynamics are not known or are known to be very good, limits excluding feel system are
 - No greater than 0.09 sec in pitch or roll
- Use criteria for all amplitudes of control input, up to maximum possible
 - Examine frequency-sweep results if coherence drops

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